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# **motionbot Documentation**

***Release <https://github.com/dof2bot/motionbot/releases/>***

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**motionbot** is controlled relay-interface station for automatization.

The README is used to introduce the tool and provide instructions on how to install the tool, any machine dependencies it may have and any other information that should be provided before the tool is installed.



## INSTALLATION

Navigate to release [page](#) download and extract release archive.

To install **motionbot** type the following

```
in progress
```





## DEPENDENCIES

**motionbot requires next modules and libraries** in progress



## PROJECT STRUCTURE

**motionbot** is based on POP.

<b>in</b> progress
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## COPYRIGHT AND LICENCE

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